

(ISO/IEC - 27001 - 2005 Certified)

SUMMER-2016 EXAMINATION

Subject Code: 17619

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Important Instructions to examiners:

1) The answers should be examined by key words and not as word-to-word as given in the model answer scheme.

2) The model answer and the answer written by candidate may vary but the examiner may try to assess the understanding level of the candidate.

3) The language errors such as grammatical, spelling errors should not be given more importance. (Not applicable for subject English and Communication Skills).

4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by candidate and model answer may vary. The examiner may give credit for any equivalent figure drawn.

5) Credits may be given step wise for numerical problems. In some cases, the assumed constant values may vary and there may be some difference in the candidate's answers and model answer.

6) In case of some questions credit may be given by judgment on part of examiner of relevant answer based on candidate's understanding.

7) For programming language papers, credit may be given to any other program based on equivalent concept.

.....

Marks				
1. a) Attempt any THREE of the following:	12			
i) State four different types of measuring instruments used while checking signals for system	04			
diagnosis.				
Answer : (Note: Any Four)				
Types of measuring instruments used while checking signals for system diagnosis:				
i. Digital multi-meters- It is used for measuring voltage, amperage, resistance, continuity etc.				
while checking the circuit.				
ii. Oscilloscope – It is used for checking signal waveform of the circuit.				
iii. Thermometers – It is used for measuring the temperature of the system.				
iv. Battery testers – It is used for testing the various parameters & conditions of the battery.				
v. Lux meters- It is used for measuring the intensity of light of the system.				
vi. Frequency meters- It is used for frequency.				
ii)With a neat sketch describe the working of idle speed actuator.	04			
Answer: Idle speed actuator: (Note: Equivalent Sketch- 2 marksand Working- 2 marks)				
Throttle Air Bypasses Idle Air				
Body Throttle Mater or Selevoid				
Valve Motor of Solehold				
Air	02			
	02			
From PCM				
IAC Valve				
Throttle				
Valve				



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Working:

In throttle body and port fuel injection systems, engine idle speed is controlled by passing a certain amount of air flow past the throttle valve in the throttle body housing. The IAC system consists of an electrically controlled stepper motor or actuator operated by the ECM. The ECM controls the idle speed by opening and closing the air passage into the intake manifold as shown in the figure. The ECM/PCM calculates the amount of air required for smooth idling based on input data such as coolant temperature, engine load, and engine speed and battery voltage. The ECM/PCM the signals the IAC motor to extend or retract the idle air control valve in the air bypass channel.	02
iii) Draw a neat block diagram to indicate measurement of temperature in vehicle instrumentation.	04
Answer: (Note: Equivalent labeled block diagram - 4 marks)	
Temperature measuring instrument:	04
iv)State the different types of computer memories. Enlist the function of read only memory.	04
 Answer:(<i>Note: Any four types- 3 marks and Function of ROM- 1 marks</i>) Explanation of Types of computer memory:(Any Three – 3 mark) 1. Read only memory (ROM) contains a fixed pattern of 1s and 0s that represent permanent stored information. ROM contains the basic operating parameters for the vehicle. This information is used to instruct the computer on what to do in response to input data. The CPU reads the information contained in the ROM, but it cannot write to it or change it. ROM memory is not lost when power to the computer is lost. 2. PROM: (Programmable Read only Memory) the information in PROM is used to define or adjust the operating parameters held in ROM. It contains specific data that pertains to the exact vehicle in which the computer is installed. 3. EPROM: Erasable Programmable read only memory is similar to the PROM except its contents can be erased to allow new data to be installed. 	03

4. EEPROM: Electrically Erasable Programmable read only memory allows changing the



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- **5. RAM: Random access memory (RAM).** The RAM will store temporary information that can be read from or written to by the CPU.
- 6. Keep Alive memory (KAM) is a variation of RAM. KAM is connected directly to the battery through circuit protection devices. For example, the microprocessor can read and write information to and from the KAM, and erase KAM information. However, the KAM retains information when the ignition switch is turned off. KAM will lost when the battery is disconnected, if the battery drains too, or if the circuit opens.

Function of Read only memory (ROM):

- i. It contains a fixed pattern of 1s and 0s that represent permanent stored information.
- ii. ROM contains the basic operating parameters for the vehicle. This information is used to instruct the computer on what to do in response to input data. The CPU reads the information contained in the ROM, but it cannot write to it or change it.
- iii. ROM memory is not lost when power to the computer is lost.

1. b) Attempt any ONE of the following:

i) With a neat sketch describe the construction and working of oxygen sensor.

Answer: Construction & working of Oxygen sensor: (*Note: Construction withfigure-4 mark and Working-2 mark*)

Construction: The core of the sensor consists of a hollow ceramic bulb or tube like structure coated with a platinum film and a protective coating. Surrounding that is a metal shield with perforations to allow exhaust gases to come in contact with the bulb. The inside of the bulb is vented to the atmosphere.



Operation:

The oxygen sensor operates on the basis of a difference between the oxygen partial pressure of atmospheric air and the partial pressure of oxygen in the exhaust gas. Figure shows that the sensor element is essentially a cell (battery). The plates are made from platinum which have a layer of ceramic zirconia between them which acts as an electrolyte. The platinum plates acts as a catalysts for the oxygen which makes contact with them, and they are also used to conduct electricity away from the sensor. The catalyzing action that takes place when oxygen contacts the platinum plates causes the transport of oxygen ions through the electrolyte and this creates the electric current that gives rise to the e.m.f (voltage) of the sensor.

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Electronic suspension system:-

The control system for a typical active suspension system is shown in the block diagram. It is in the form of a micro controller or microprocessor base digital controller the inputs for each sensor are sampled converted to digital format and stored in the memory the sampling is typically at about 500 Hz. In this control configuration the relative position and motion of the wheel of the wheel body(sprung mass) acceleration, the relative position and motion of the wheel body. (unsprung or sprung mass) the steering wheel input and vehicle speed. The body acceleration measurement can be used to evaluate ride quality. The controller dies this by computing weighted average of spectrum of the acceleration the relative body or wheel motion can be used to estimate tire force.



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2. Attempt any FOUR of the following	16
a)Justify the use of semi conductor diode used in voltage regulation of charging system.	04
Answer:(<i>Note:- Justification- 4 Marks</i>) Justification of Use of semiconductor diode in voltage regulation: To prevent the vehicle battery from being overcharged the regulated system voltage should be kept below the gassing voltage of the lead-acid battery.Accurate voltage control is vital with the ever-increasing use of electronic systems.Voltage regulation is a difficult task on a vehicle alternator because of the constantly changing engine speed and loads on the alternator. The output of an alternator without regulation would rise linearly in proportion with engine speed. Zener diode is used as the sensing element in an electronic regulator. A Zener diode is designed to operate in the break-down region. At the point that Zener voltage is reached, a large current flows in reverse bias. This prevents voltage from climbing any higher. This makes the Zener diode an excellent component for regulating voltage. If the Zener diode is rated at 15 volts, it will not conduct in the reverse direction when the voltage is below 15 volts. At 15 volts it will conduct and the voltage will not increase over 15 volts. If a semi-conductor diode is reverse-biased it will not conduct current. However, if the	04
reverse voltage is increased, a voltage level will be reached at which the diode will conduct in the reverse direction. This voltage is called Zener voltage. Reverse current can destroy a simple PN-type diode, but the diode can be dropped with materials that will withstand reverse current.	
b)State the importance of manifold absolute pressure sensor. Describe the principle on which this sensor works.	04
Answer: (Note: Importance- 02 marks, Description any one type of principle – 02 marks) Importance of manifold absolute pressure sensor: The manifold absolute pressure sensor provides instantaneous manifold pressure information to the engine ECU. The data is used to calculate air density and determine the engine's air mass flow rate, which in turn determines the required fuel metering for optimum combustion and influence the advance and retard of ignition timing. The MAP sensor can also be used in OBD II applications to test the EGR valve for functionality.	02
 MAP sensor principle:(Any one) There are three different types of principles on which MAP sensor works. 1. Strain gauge type:- An external tensile force/ compressive force increases/decreases the resistance by elongating/contracting it. 2. Variable capacitance type:- The capacitive transducer comprises of two parallel metal plates that are separated by the material such as air, which is called as dielectric material. In this type the distance between two plates is variable it changes its capacitance value. This change in capacitance can be measured easily and it is calibrated against the input quantity. 3. Variable inductance type:- The inductance of the coil is altered by varying position of an iron cylinder placed in the centre of the coil due to change in pressure against the diaphragm. This change in inductance is directly reflected on change in pressure.	02



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Tire Pressure Warning System Valve & Transmitter

- 1. Combination Meter: Transmits the vehicle speed signal to the tire pressure warningsystem ECU for vehicle speed correction.
- 2. Tire Pressure Warning Light: Turns ON or blinks to warn the driver in accordance with the signal from the tire pressure warning system ECU, Displays the 2-digit DTC (Diagnostic Trouble Code).
- 3. Tire Pressure Warning System Reset Switch: The appropriate air pressures of the tires currently mounted on thevehicle are stored in the tire pressure warning system ECU by operating the tire pressure warning system reset switch.
- 4. Tire Pressure Warning System Valve & Transmitter: Detects the inflation pressure and internal temperature of the tire and transmits the measured value and the ID number to the tire pressurewarning antenna & receiver.



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5. Tire Pressure Warning System Antenna & Receiver: Receives the tire pressure warning system valve & transmitter signal and transmits this data to the tire pressure warning system					
ECU.					
6. Tire Pressure Warning System ECU: Receives the data from the tire pressure warning					
system antenna & receiver and monitors the tire inflation pressure. When the tire pressure					
warning system ECU detects a drop in the tire inflation pressure or a system malfunction, it					
outputs therespective signal to the combination meter.					
d)Write the applications of following instruments:	04				
(i) Lux Meters					
(ii) Battery tester					
Answer: (Note: Any Two applications of each)					
<i>i.</i> Lux Meters: - (Any Two – 1 Mark each)					
a. Used to measure light intensity.	02				
b. It is used in photography and video filming.					
c. Check intensity of lights in the automatic ON/OFF headlight system and					
automatic headlight dimming system.					
<i>ii.</i> Battery Tester: - (Any Two – 1 Mark each)					
a. Voltage measurement.	02				
b. Resistance measurement.					
c. CCA value Measurement.					
d. Battery condition.					
e. Battery load test etc.					
e) Draw a neat block diagram to show the configuration of closed loop control system.	04				
Answer: (Note: Block diagram -4 marks. Credit should be given to equivalent Sketch)					
Control	04				
-Input Controller	-				
Sigilal					
▲ · · · · · · · · · · · · · · · · · · ·					
Measuring					
Flement					
	l				
Closed Loop System	l				
OR					
	1				



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In the binary system, whole numbers are grouped from right to left. Because the system uses



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only two digits. The first portion must equal a 1 or a 0. To write the value of 2, the second position must be used. In binary, the value of 2 would be represented by 10 (one two and zero ones). To continue, a 3 would be represented by 11(one two and one one). Figure illustrates the conversion of binary numbers to digital base ten numbers. For example, if a thermistor is sensing 150 degrees, the binary code would be 10010110. If the temperature increases to 151 degrees, the binary code changes to10010111.

Decimal number	Binary number code 8 4 2 1	Binary to decimal conversion
0	0000	= 0 + 0 = 0
1	0001	= 0 + 1 = 1
2	0010	= 2 + 0 = 2
3	0011	= 2 + 1 = 3
4	0100	= 4 + 0 = 4
5	0101	= 4 + 1 = 5
6	0110	= 4 + 2 = 6
7	0111	= 4 + 2 + 1 = 7
8	1000	= 8 + 0 = 8

b)Distinguish between primary memory and volatile memory.

Answer:(Note: Credit should be given to equivalent answer) <u>Primary Memory:-</u>

Primary memory consists of two types of memory, read-only memory and read/write memory. Read-only memory (ROM) usually holds the permanent directions or instructions and data by which the individual computer is governed. Read means to find out what number is stored in a specific address. Write means to put a new number into a specific address. As the name implies, the microprocessor of a computer cannot change the data stored in its ROM. That is not to say that the data in a ROM can never be changed. The memory that remains after power is turned off is "nonvolatile" and is referred to as firmware.

The read write (R/W) memory is designed to hold changing data. To change these data, very specific directions are required in the program. These are still data that the microprocessor uses to function correctly.

Volatile Memory:-

"Volatile" memory is the section of computer memory that is active as long as the power is on. If the power is turned off, all the binary codes in the RAM (random access memory) are lost. When power to the RAM is reestablished, the registers are all empty but are ready to accept input. The microprocessor writes numbers into the registers of the RAM or reads those data as it processes. Data from sensors may be stored or computed data may be written into these registers. Some of the stored data may be read to make further computations.

02

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c)Describe the application of Global positioning system used as a navigation system in cars.	04
Answer: (Note: Description-4 marks and Credit should be given to Equivalent sketch)	04
Global positioning system (GPS):	
The Global Positioning System (GPS) is a space-based navigation system that provides	
location and time information in all weather conditions, anywhere on or near the Earth where there	
is an unobstructed line of sight to four or more GPS satellites.	
GPS systems are made up of 3 segments:-	
• Space Segment (SS)	
• Control Segment (CS)	
• User Segment (US)	
1. Space Segment:	
GPS satellites fly in circular orbits at an altitude of 20,200 km and with a period of 12	
hours. Powered by solar cells, the satellites continuously orient themselves to point their solar	
panels toward the sun and their antenna toward the earth. Orbital planes are centered on the	
Earth. Each plane has about 55° tilt relative to Earth's equator in order to cover the polar regions.	
Each satellite makes two complete orbits each sidereal day. Sidereal - Time it takes for the	
Earth to turn 360 degrees in its rotation. It passes over the same location on Earth once each day.	
2. Control Segment: The CS consists of 3 entities:	
i.Master Control Station:-The master control station, located at Falcon Air Force Base in	
Colorado Springs, Colorado, is responsible for overall management of the remote	
monitoring and transmission sites.	
ii.Monitor station: - Each of the monitor stations checks the exact altitude, position, speed,	
and overall health of the orbiting satellites. The control segment uses measurements	
collected by the monitor stations to predict the behavior of each satellite's orbit and clock.	
The prediction data is up-linked, or transmitted, to the satellites for transmission back to the	
users.	
iii.Ground Antennas: - Ground antennas monitor and track the satellites. They also transmit	
correction information to individual satellites.	
3. User Segment: The user's GPS receiver is the US of the GPS system. GPS receivers are	
generally composed of an antenna, tuned to the frequencies transmitted by the satellites,	
receiver-processors, and a highly-stable clock, commonly a crystal oscillator. They can also	
include a display for showing location and speed information to the user.	
Space segment	
and the second sec	
under working the second second	
Charles Charle	
Control Segment	
Fig. Global Positioning System	



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d) List the six steps followed during component testing. Describe any one step	04
Answer (Note: List - 3 marks and Description any one- 1 mark)	
Six step approach for components testing \cdot . (Six. $\frac{1}{2}$ mark each)	
1 Collect evidence	
2 Analyze evidence	
3 Locate the fault	
4 Find the cause of the fault and remedy it	03
5. Rectify the fault (if different from 4)	05
6. Test the system to verify that repair is correct	
0. Test the system to verify that repair is contect.	
Six step approach for components testing:- (Any One- 1 mark)	
1. Collect Evidence- Collecting evidence means looking for all the symptoms that relate to the	ne.
fault and not jumping to conclusions, e.g. because the system is controlled by an ECU	it
must be the ECU that is at fault. In order to collect the evidence it is necessary to know	TC W
which components on the vehicle actually form the part of the faulty system. This is when	re 01
sound basic skills come in If an engine control system is malfunctioning because or	
cylinder has poor compression it is important to discover this at an early stage of the	
diagnostic process	
2 Analyze Evidence. In the case of poor compression on one cylinder given above as	n
example the analysis would take the form of tests to determine the cause of lo	111 XX7
compression E g burnt value blown head gasket etc. The analysis of evidence that	ic
performed will vary according to the system under investigation. But these steps a	ro
obviously important	
3 I ocate the fault - The Procedure for doing this on an electronics system varies according t	to
the type of test equipment available. It may be the case that the system has some sel	.0 f
diagnostics which will read you to the area of the system which is defective. Let us assume	1-
that this is the case and the self diagnostics report that an engine coolant temperature sense	or
is defective. How do you know whether it is the sensor, or the wiring between it and the	
remainder of the system? A gain this is where a good basic knowledge of the make up of the	
system is involveble	IC
4 Find the cause of the fault and remody it. With electronic system repair it is often the case	20
4. Find the cause of the fault and femery it- with electronic system repair it is often the case that a replacement unit must be fitted. However, this may not be the end of the matter. If the	
unit has failed because of some fault external to it it is important that this cause of failure	ic
found and remedied before fitting the new unit. It is often not just a metter of fitting a new	15
iound and remedied before fitting the new unit. It is often not just a matter of fitting a ne	w
unit. 5 Cive the system a theraugh test Testing after repair is an important aspect of vehicle wo	rk
s. Give the system a thorough test -resting after repair is an important aspect of vehicle wor	.r.
intermittent faulte, such testing's may need to be extended because the fault may only equi	JI Jr
when the angine is het and the vehicle is being used in a particular way	11
6 Tost the system to verify that repair is correct. It is mandatory to test the system as that	i+
u. Test the system to verify that repair is correct- it is mandatory to test the system so that will verify that the store followed during the testing are correct. However, the store so that	
will verify that the steps followed during the testing are correct. However we can com	ie
across any fault men we have to follow the stepwise procedure of testing.	



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e) Describe the procedure used to indicate the TDC reference mark of cylinder No.1 to the ECM.	04
Answer:(Credit should be given to equivalent procedure)	
Procedure used to indicate the TDC reference mark of cylinder No.1 to the ECM:	
 The camshaft and crankshaft position sensors are collectively used to determine the exact position of the number 1 cylinder in respect to top dead center on the compression stroke. These two sensors are either a Hall Effect or magnetic reluctant controlled devices. The Hall Effect-type sensor makes use of a notched ring and an electromagnetic sensor. The sensor is stationary while the notched ring, called an interrupter, passes through it. Passing the notches on the wheel through the sensor produces a signal, which is then sent to the Power train Control Module (PCM) representing the position of the crankshaft or camshaft relative to top dead center on the number 1 cylinder. The magnetic reluctant sensor uses a rare earth magnet and a winding of wire. As the trigger wheel passes near the sensor it generates an AC voltage signal, which is sent to the PCM. The introduction of the crank and cam sensors helped to eliminate the variances in ignition timing signals so prevalent in a distributor controlled ignition engine. 	04
4.a) Attempt any <u>THREE</u> of the following:	16
i) Enlist the purpose of photo-diode and LED used in ignition system.	04
Answer:(<i>Note: credit should be given to equivalent answer and sketch</i>) Purpose of photo-diode and LED used in ignition system: An optical triggering mechanism consist of a light emitting diode (LED) and light sensitive photo- diode (photocell or receptor) and also a slotted disc called a light beam interrupter . The slotted disc is attached to the distributor shaft. The LED and photocell are situated over and under the slotted disc opposite of each other. As the slotted disc rotates between the LED and the photo-diode, light from LED shines through the slots. The intermittent flashes of the LED are translated into voltage pulses by the photocell. Where the voltage signal occurs, the control unit turns ON the primary circuit. When the disc interrupts the light and the voltage signal is not given the control system turns the primary circuit OFF causing the magnetic field in the primary coil to collapse and sending a high voltage current to spark plug through secondary winding.	04
INTERRUPTER WHEEL SOURCE RECEPTOR	



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3. Testing of Throttle position (TP) sensor:- Following procedure is followed to diagnose a TP sensor:	
• With the ignition switch in the RUN position, connect a voltmeter from the sensor signal wire to ground.	
• Slowly open the throttle and observe the voltmeter.	
• The voltmeter reading should increase smoothly and gradually.	
• Typical TPS voltage readings are 0.5V to 1V with the throttle in the idle positions, and 3.5V to 4.5V at wide open throttle.	
• Always refer to the vehicle manufacturer's specifications.	
• If the TPS does not have the specified voltage or if the voltage signals is erratic, replace the sensor.	
iv) Describe the testing procedure to conduct a test on any one automotive sensor.	04
Answer: (Note: Any one sensor testing procedure - 4 marks)	
1. Testing of Oxygen Sensor: - Following procedure is followed to diagnosean oxygensensor.	04
• Disconnect the connector of the oxygen sensor.	
• Start the engine and warm-up for 2 minutes at 3000 rpm under no load conditions.	
• Raise the engine speed to 4000 rpm and release the throttle suddenly for at least 5 times.	
• Within one minute after the engine has been warmed up, measure the voltage between	
the connector terminal and body ground.	
• The voltage should be below 0.4 Volts.	
• Replace the oxygen sensor if the voltages are out of the above range.	
2. Testing of Intake air temperature (IAT)sensor and Engine coolant temperature (ECT)	
sensor: - Following procedure is followed to diagnose an IAT sensor.	
• Remove IAT sensor from the engine.	
• Place it in a container of water with thermometer.	
• Make sure that more than half of the connector is submerged in the water.	
• Connect a pair of ohmmeter leads to the sensor terminals.	
• Heat the water in the container and measure the resistance at different temperatures.	
• The sensor should have the specified resistance 0.98 to 1.34 K Ω at 40° C and 0.22 to 0.35 K Ω at 80 ⁰ .	
• Replace the sensor if the resistance values are outside the range.	
3. Testing of Throttle position (TP) sensor:- Following procedure is followed to diagnose a TP sensor:	
• With the ignition switch in the RUN position, connect a voltmeter from the sensor signal wire to ground	
• Slowly open the throttle and observe the voltmeter	
 Slowly open me unome and observe me volumeter. The voltmeter reading should increase smoothly and gradually. 	
 The volume of reading should increase smoothly and gradually. Typical TPS voltage readings are 0.5V to 1V with the throttle in the idle positions, and 	
• Typical 115 voltage readings are 0.5 v to 1 v with the unotice in the positions, and	

3.5V to 4.5V at wide open throttle.

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- Always refer to the vehicle manufacturer's specifications.
- If the TPS does not have the specified voltage or if the voltage signals is erratic, replace the sensor.

4. Manifold absolute pressure (MAP)sensor: - Following procedure is followed to diagnosean ECT sensor.

- Turn the ignition ON (engine OFF).
- Measure the voltage (or frequency) of the sensor output.
- Using a hand operated vacuum pump, apply vacuum to the sensor.
- A good pressure should change voltage (or frequency) in relation to the applied vacuum.
- If the signal does not change or the values are out of range according to the manufacturer's specifications, the sensor must be replaced.

4. b) Attempt any ONE of the fo	ollowing:	
---------------------------------	-----------	--

i) Describe the procedure of conversion of signals from analog to digital.

Answer: (Note: Description with equivalent sketch- 06 marks)

Analog to Digital Conversion:

Analog to digital conversion is necessary because many sensor signals are of analog (varying voltage) form. In order for the control computer (ECU) to function these analog signals must be converted to binary codes (digital signals). Conversion from an analog voltage to a digital code can be done in a number of ways. Figure shows one type of A/D converter that is known as a 'flash' converter.

The flash converter consists of four comparators and an encoder circuit which takes the comparator outputs and converts them into a binary code. An electronic comparator is a circuit which continuously compares two signals. One of the inputs, at each comparator is a reference voltage. When the input voltage matches the reference voltage the comparator outputs logic 1. The reference voltages shown in the figure are 1V up to 4 V. Table shows the input/output performance of the converter.



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P								
A/D converter input	Compara	tor of	atputs	Encoder	outp	outs		
Voltage range	$A \qquad B$	<u>C</u>	D	0	0	0	-	
$\frac{0-1}{1}$	$\frac{0}{1}$	0	0	0	0	0		
1-2V	<u>1 0</u>	0	0	0	0	<u>l</u>	-	
2-3V	1 1	0	0	0	1	0		
3-4V	1 1	1	0	0	1	1		
4-5V	1 1	1	1	1	0	0		
ii) Define error. State two types of e	rrors.							06
 Answer: (Note: Definition -2 mark Error: An error is defined as: "The "If two persons use the same instru- not essential that they may get the measurements. This difference is reference is reference is reference. Types of error: (Any two- 2 mark 1) Personal error: An error comes into play because "PERSONAL ERROR". Personal error comes into existence procedure adopted by the personal error comes into existence procedure adopted by the personal error. Systematic error: The type of error arises du "SYSTEMATICERROR". Gen negative error. Systematic error 3) Random Error: The error produced due to sudde ERROR". Forexample:During sudden change difference (voltage). It is an makingmeasurement. 	s, Any two type difference between the for mean the same result ferred to as an as each) use of faulty the due to make on making mean to defect erally it is of can be remote en change in the in temperate accidental en	t in called by a surer fts. The proce ing an easurer t in called by a expension ure, clar rror a	a mark) the meas nent for a nere may ROR". edure a edure a error in ment. the n "ZERO y correct erimental hange ir nd is b	sured value a finding the arises a d dopted by reading a neasuring ERROR". ing measure conditions humidity, eyond the	and t same liffer the scale devi- it r emer s is fluc con	the actual value e measurement rence betweet observer is e. It is due to ce is knownay be posit at device. called "RAN ctuation in posit trol of the	ue. nt, it is n their called faulty vn as tive or NDOM otential person	02
5. Attempt any FOUR of the following:					16			
a) Draw a neat block diagram a	nd describe C	CAN b	us syster	n in automo	biles	8.		04
Answer: (<i>Note: Description of CA</i> CAN bus system: CAN (Controller Area Network) developed by the Robert Bosch Com protocol that connects electronic con	<i>N Bus system</i> is an examp npany in Gerr ntrol modules	le of many.	arks & B an autor CAN is ors and a	<i>lock diagra</i> motive digi a serial sync ctuators.	m – tal c chror	02 marks) data system. nous commun	It was ication	02



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The twisted pair of the CAN bus system minimizes electrically initiated interference and

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virtually eliminates the possibility of messages becoming corrupted. The major feature of the CAN bus system are: Priority controlled message transmission. i. Low cots through the use of a low cost twisted two wire cable and use of simple protocol ii. with low power demand. A data transfer rate up to 1MBPS for the high speed CAN (CAN-C) and up to 125KBPS for iii. the low speed CAN (CAN-B) High reliability of data transfer iv. **Block Diagram of CAN Bus System:** A typical example of the CAN bas system used in Rover vehicle is described below. A Two wire CAN bus that can operate at high data transmission speeds of up to 500k band (500000bits/sec) is shown in the below figure. 1. Automatic transmission control unit 2. Engine control module 3. ABS/ Traction control ECU 4. Instrument Pack. 02 2 1 CAN bus Bus Terminator 3 Δ A CAN bus b) State the need of electronic power steering. Enlist different sensors used in the system. 04 Answer:(Note: Need-02 marks,List of sensors- 02 marks) Need of Electronic power steering: (Any Two- 1 mark each) An electronically controlled power steering adjusts the steering boost adaptively to the 02 ٠ driving conditions. Using electronic control of power steering, the available boost is reduced by controlling a • pressure relief valve on the power steering pump. Reduce the driving efforts of the driver. Reduce the fatigue of the driver. To avoid under-steer & over-steer condition of the vehicle.

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The different sensors used in the system are: (Any Two- 1 mark each)	02
2. Torque sensor	02
2. Vahiala speed sensor	
5. Venicie speed sensor	
c)State the application of oscilloscope as a type of measuring instrument used in system	04
diagnosis.	
Answer:(Note: Equivalent description- 04 marks)	
• The oscilloscope may be considered as a very fast reacting voltmeter that reads and displays	
voltages.	
• The oscilloscope allows the technician to view the voltage over time. These voltage readings	
• Today most technicians use a variation of the oscilloscope called a lab scope which is a	
• Today most technicians use a variation of the oscinoscope caned a lab scope which is a small portable unit	04
• The screen of a lab scope is divided into small divisions of time and voltage. The division of	_
screen creates a grid pattern.	
• Time is represented by the horizontal movement of the waveform. Voltage is measured with	
the vertical position of the waveform.	
For example:	
The vertical scale can be adjusted so each division represents 0.5 volts and the horizontal scale	
can be adjusted so each division equals 0.005 (5 milliseconds). This allows the technician to view	
small changes in voltage that occurs in a very short period of time. An example could be observing a	
fuel injector activity when certain changes occur.	
	0.4
d) State the importance of display devices used in automotive applications. List any two types of	04
digital display devices.	
Answer: (Note: Importance- 02 marks, List- 02 marks)	
Function of any visual display is to communicate information to the desired level of accuracy	
Mostdisplays used in the vehicle must provide instant databut the accuracy is not always important	02
Analoguedisplays can provide almost instant feedback from oneshort glance. For example, if the	02
needle of the temperaturegauge is about in the middle then the drivercan assume that the engine	
temperature is withinsuitable limits. A digital read-out of temperaturesuch as 98 ° C would not be as	
easy to interpret. Thisis a good example as to why even when digital processingand display	
techniques are used, the actualread-out will still be in analogue form. Numerical and other forms	
of display are, however, used for many applications.	
The different types of digital display devices are: (Any Two-1 mark each)	
1. Fuel quantity level measurement	02
2. Coolant temperature measurement	02
3. Vehicle speed measurement	
4. Oil pressure measurement	



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Function of components:

1. Clock:

The clock in a computer sets the pace at which processing occurs. It is the basic input to the control unit. The clock is an electronic circuit that utilizes the piezoelectric effect of a quartz crystal to produce accurately timed electrical pulses that are used to control the actions of the computer.

Clock speeds are measured in the number of electrical pulses generated in one second. One pulse per second is 1 Hertz and most computer clocks operate in millions of pulses per second. One million pulses per second is 1 megahertz (1 MHz).

2. Input/output:-

This unit has the responsibility of accepting data from sensors or other types of inputs and converting those data to an acceptable form to send on to the processor. The input/output also accepts data from the processor and converts them into an acceptable form to be sent out to the actuators. The input/output unit (I/O) also takes orders from the control unit concerning when to send outputs to the actuators or when to accept inputs from the sensors.



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f) State the importance of use of electronics in the automobile. Mention any four potential	04
applications of the same.	
Answer:(Note: Importance:2 marks and Applications:2 marks)	
Importance of use of electronics in automobiles:	02
Standardization of functional interfaces	
• Share and reuse the existing components	
Comprehensive safety	
• A high degree of comfort	
• Low energy consumption	
Minimal pollutant emission	
• Improved quality and reliability of automotive.	
Some of the present and potential applications for electronics are:- (Any Four)	
1. Electronic engine control for minimizing exhaust emissions and maximizing fuel economy.	
2. Instrumentation for measuring vehicle performance parameters and for diagnosis of ON-	
BOARD system malfunctions.	
3. Power train control system	02
4. Vehicle motion control	02
5. Safety and convenience	
6. Entertainment/communication/navigation	
6. Attempt any FOURof the following:	16
6. Attempt any FOURof the following:a) Given a decimal number of 25, convert it into a binary number.	16 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks)	16 04
 6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. 	16 04 04
 6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 	16 04 04
 6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 	16 04 04
 6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 	16 04 04
 6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 	16 04 04
 6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 121 	16 04 04
 6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 121 	16 04 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 25 2 121 2 60	16 04 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 25 2 121 2 60	16 04 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (<i>Note: Equivalent conversion process - 04 marks</i>) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 25 2 25 2 26 2 60 2 30	16 04 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (<i>Note: Equivalent conversion process - 04 marks</i>) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 25 2 25 2 26 2 60 2 30	16 04 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 121 2 60 2 30 11	16 04 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 121 2 60 11	16 04 04
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6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 12 2 6 1 0 1 1 Step 2: So (25)::::::::::::::::::::::::::::::::::::	16 04 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 121 2 60 11 11 2 30 11 5 5 11 2 30 11 5 2 30 11 5 5 5 5 30 1 0	16 04 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (<i>Note: Equivalent conversion process - 04 marks</i>) Convert 25 into binary number. Step 1: Given decimal number = 25 2 25 2 25 2 121 2 60 2 30 11 Step 2: So, $(25)_{10} = (11001)_2$ (25) = (11001)	16 04 04
6. Attempt any FOURof the following: a) Given a decimal number of 25, convert it into a binary number. Answer: (Note: Equivalent conversion process - 04 marks) Convert 25 into binary number. Step 1: Given decimal number = 25 $2 25$ $2 12$ $2 26$ $2 3$ $2 3$ $2 3$ 1 $2 3$ $2 3$ $2 3$ $2 3$ $2 3$ $2 3$ $2 3$ $2 3$ $2 3$ $2 3$ $2 3$ $2 3$ 3 3 3 3 4 3 4 4 3 4 4 4 4 4 4 4 4 4 4 4 4 4 4	16 04 04



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